

Coronal and heliospheric imaging instrumentation development at RAL Space

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Heritage (1)

- **RAL Space has been involved in the construction of over 200 space-based instruments***
- **...for example on AMPTE, Chase, Cluster, ERS-1, ERS-2, GOES-R, Herschel, Hinode, IRAS, ISO, Polar, SDO, SMM, SOHO, STEREO, Yokoh...**
- **...and we wish to continue in that vein!**

***as well as some ground-based instrumentation**

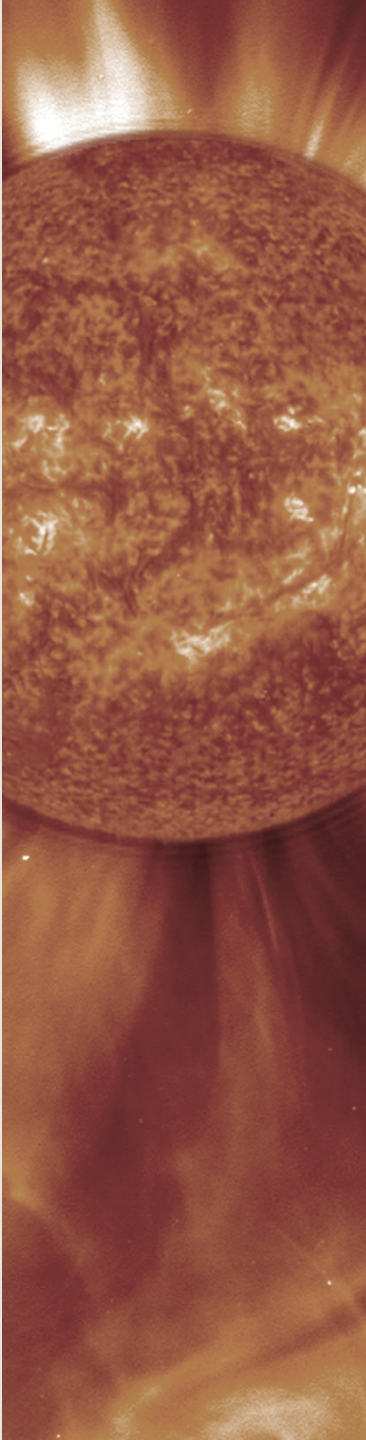


Heritage (2)

- **RAL Space staff have significant heritage in building white-light coronal and heliospheric imagers (SOHO/LASCO, Coriolis/SMEI, STEREO/HI).**
- **Over the last 6 months, in response to a variety of opportunities (and the re-emerging realization within RAL Space that scientists are actually a potential source rather than a sink of money), we have been rekindling our white-light endeavours!**

Heliospheric Imaging

- **RAL Space led the European consortium that designed and built STEREO/HI (HI PI: Richard Harrison).**
- **SO/SoloHI and SPP/WHISPR lend heavily from the STEREO/HI instrument design.**
- **PHELIX is the RAL Space polarizing heliospheric imager that was part of the payload of the recently-proposed (and sadly unsuccessful) INSTANT ESA/CAS S2 science mission (PHELIX PI: Jackie Davies).**



PHELIX: Polarizing Heliospheric Imaging eXplorer

PHELIX budgets and resources.

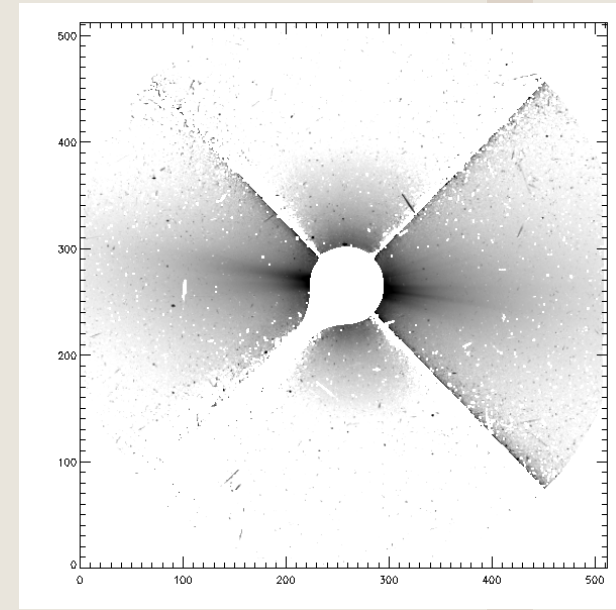
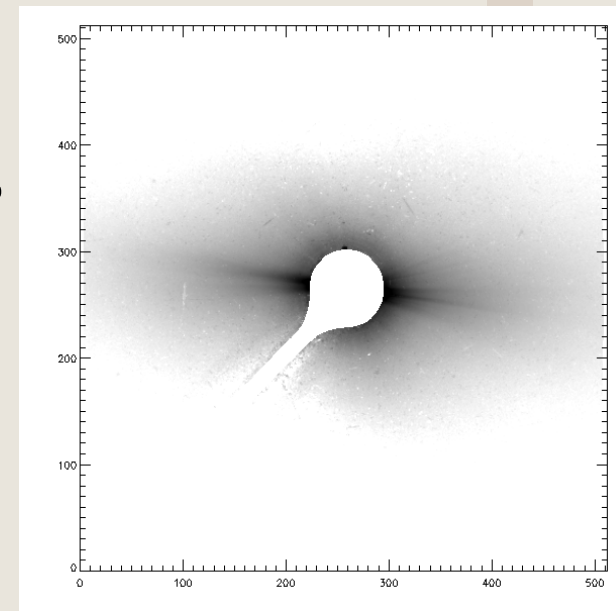
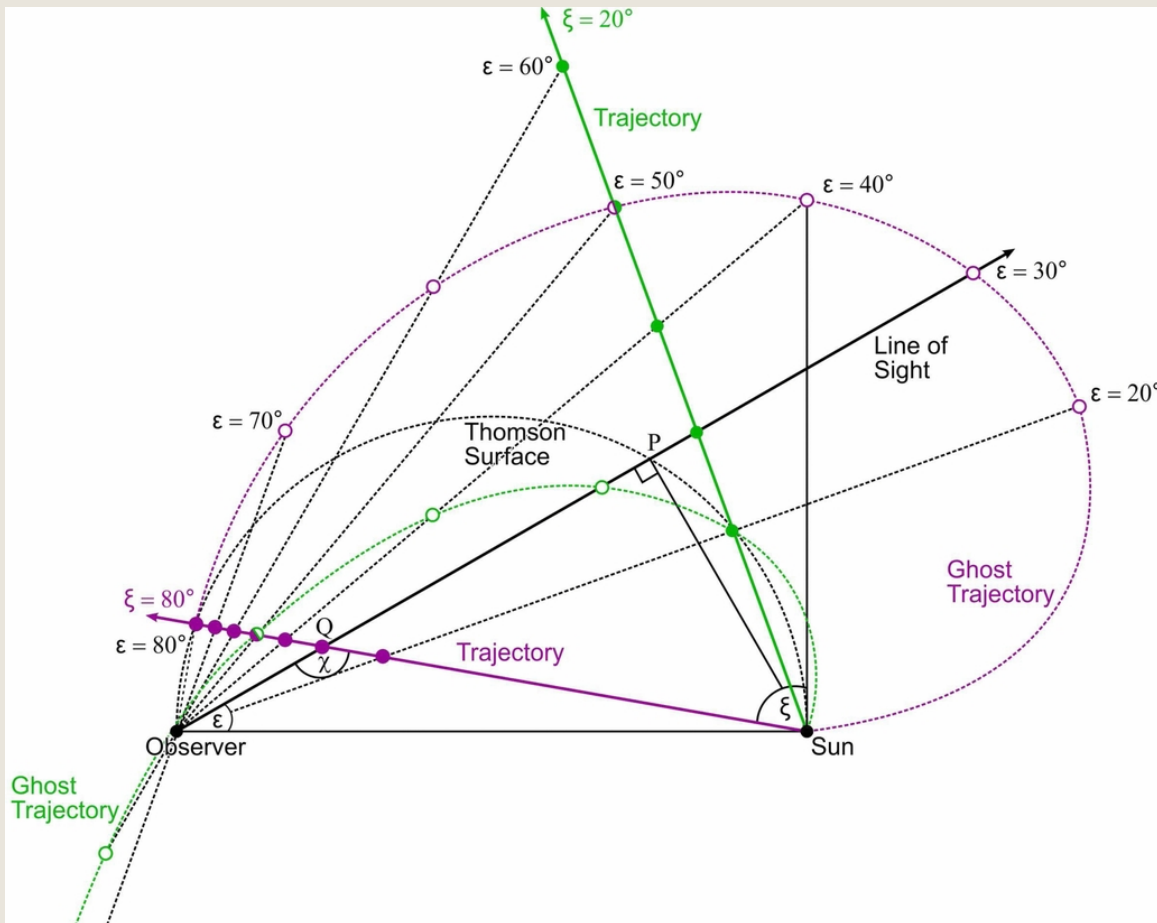
Parameter	PHELIX-1	PHELIX-2
Field-of-view diameter	30°	50°
Elongation range (FOV)	3.75° – 33.75°	20° – 70°
Spectral bandpass	630 – 730 nm	400 – 1000 nm
Image bin size (1k x 1k binning)	1.75'	2.9'
Summed image cadence	Phase 1/2: 15/30 min	Phase 1/2: 20/60 min
Polarimetry capability	N/A	Polarized images at -60°, 0° and +60°
Brightness sensitivity	$3 \times 10^{-15} \text{ B}_0$	$3 \times 10^{-16} \text{ B}_0$
Total Resource Requirements		
Mass (PHELIX / DPU)	16 kg / 4 kg (10% / 20% margins)	
Size (PHELIX / DPU)	840 x 550 x 260 mm / 250 x 150 x 60 mm	
Power	14.2 W / 6 W (10% / 20% margins)	
Pointing accuracy (3 σ)	$\pm 6'$ for PHELIX pitch axis; $\pm 1^\circ$ for yaw & roll axes	
Pointing stability (3 σ / 30 min)	21" for PHELIX pitch & yaw axes; 37" for roll axis	
Accommodation	Minimize other spacecraft units above plane of baffles	
Data product	Polarized brightness images of K coronal activity	
Telemetry rate	Phase 1: 26 kbps (1024 x 1024 images) Phase 2: 4 kbps for 512 x 512 (15.5 kbps for 1024 x 1024: burst) Beacon: 330 bps for 256 x 256, 1 hr, total brightness only	
TRL	> 6 (9 for most sub-systems)	

Why/where/how Polarize?

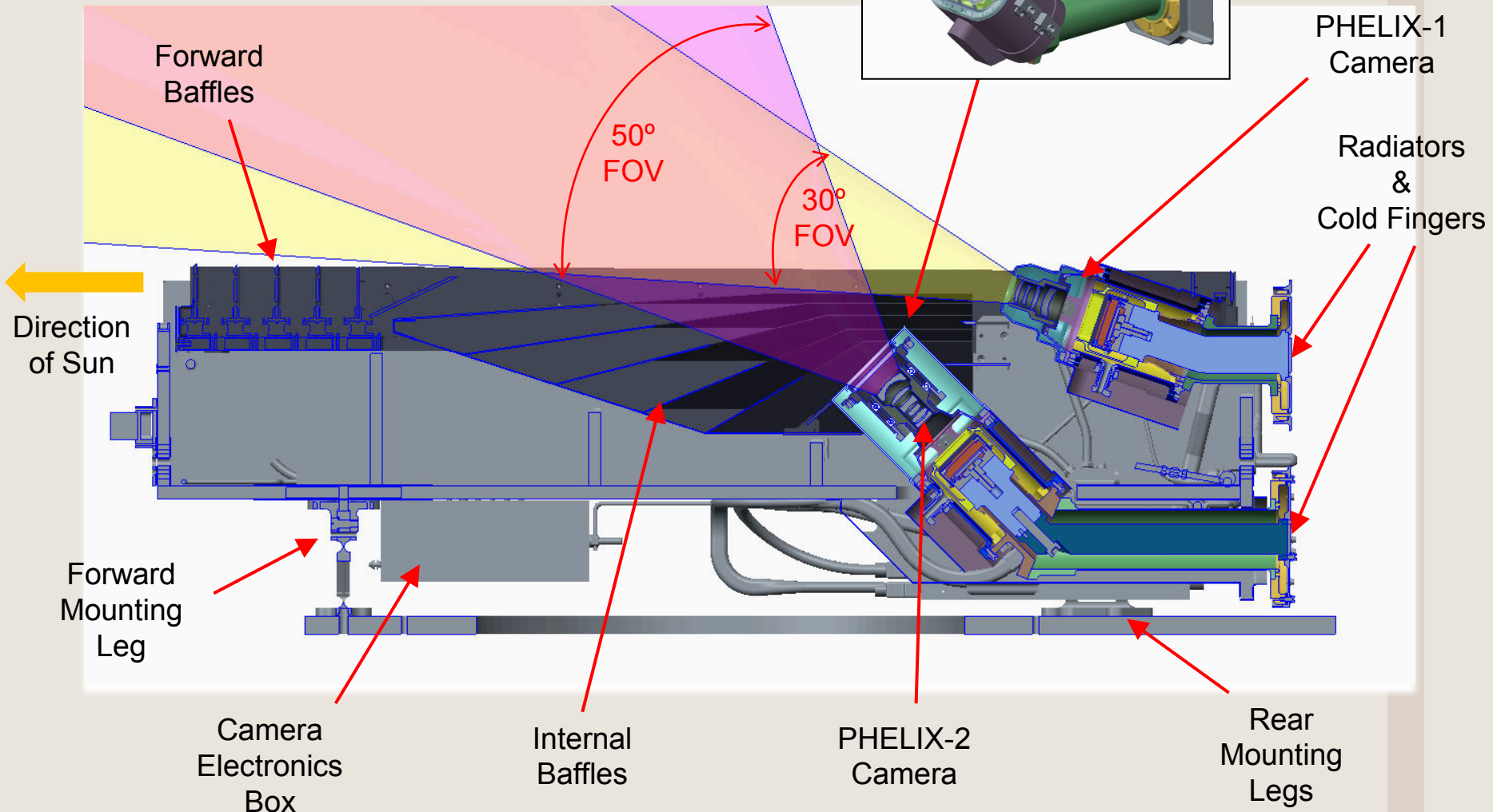
- Degree of polarization of Thomson-scattered light is high (over 50%) to beyond 100° elongation.
- The scattering function for the polarized component is more strongly peaked at the Thomson surface than for unpolarized.
- So we can use the pB/B ratio to estimate the location of a disturbance along the line of sight.
- pB/B is symmetrical about the Thomson surface. A single coronagraph can't distinguish "front" and "back-sided" CMEs.
- **However**, for a wide-angle imager we can exploit non-linearity to make that distinction as one side will lead to an unphysical trajectory.
- Because the non-linearity is greater at larger elongations, the distinction becomes greater (proposed polarization of PHELIX-2 only).
- Baselined use of 3 components (2 leaves 45° line undefined) and no clear (mass considerations – with a clear, you can't rotate a single polarizer).

Use of 2-component versus 3-component.

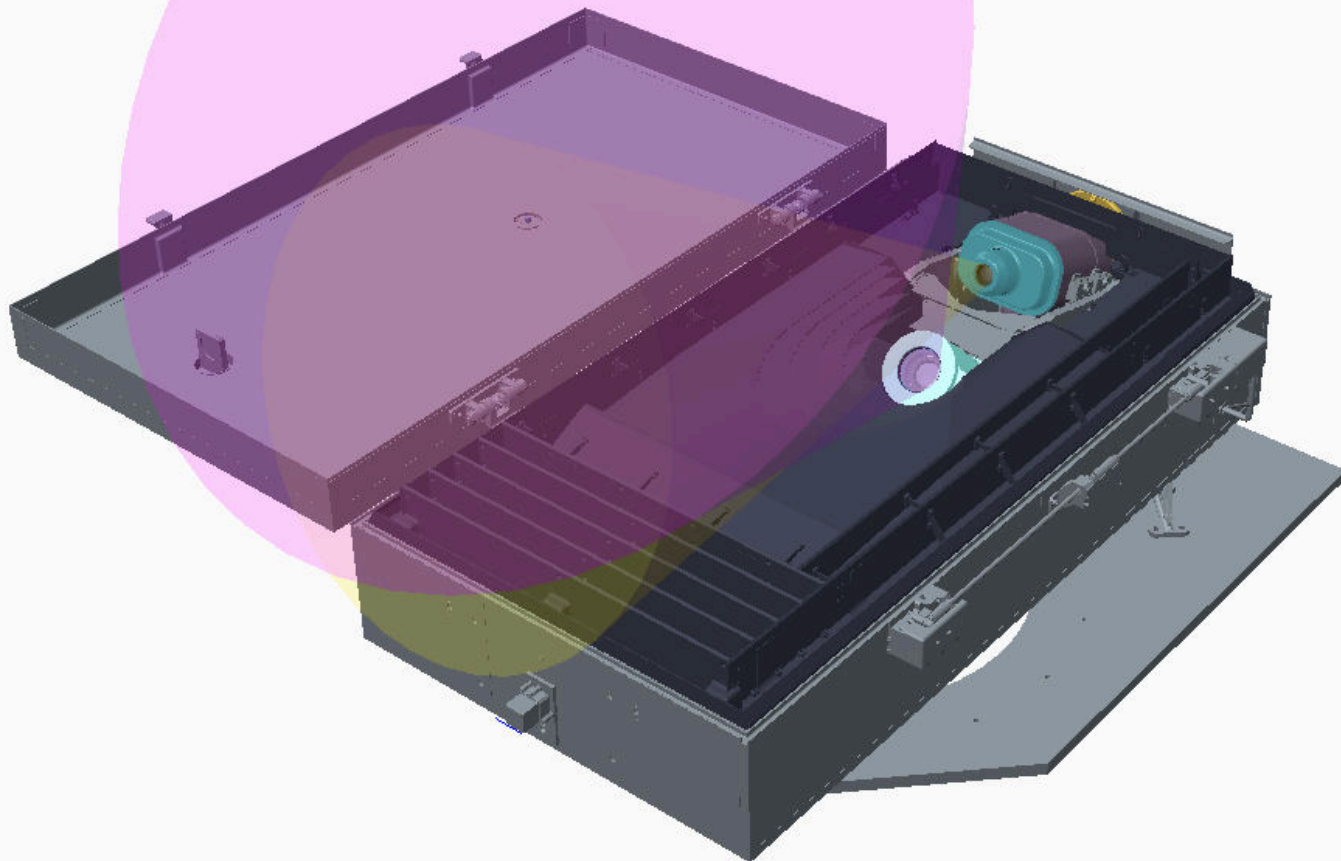
Depth perception.



PHELIX: Polarizing HELiospheric Imaging eXplorer (based on STEREO/HI)



PHELIX: Polarizing HELiospheric Imaging eXplorer



FOV implications for baffling

- There were initial suggestion to move the inner edge of the PHELIX field-of-view (FOV) inwards from its nominal STEREO/HI value (note also the FOV size of PHELIX-1 was increased from the HI-1 value).

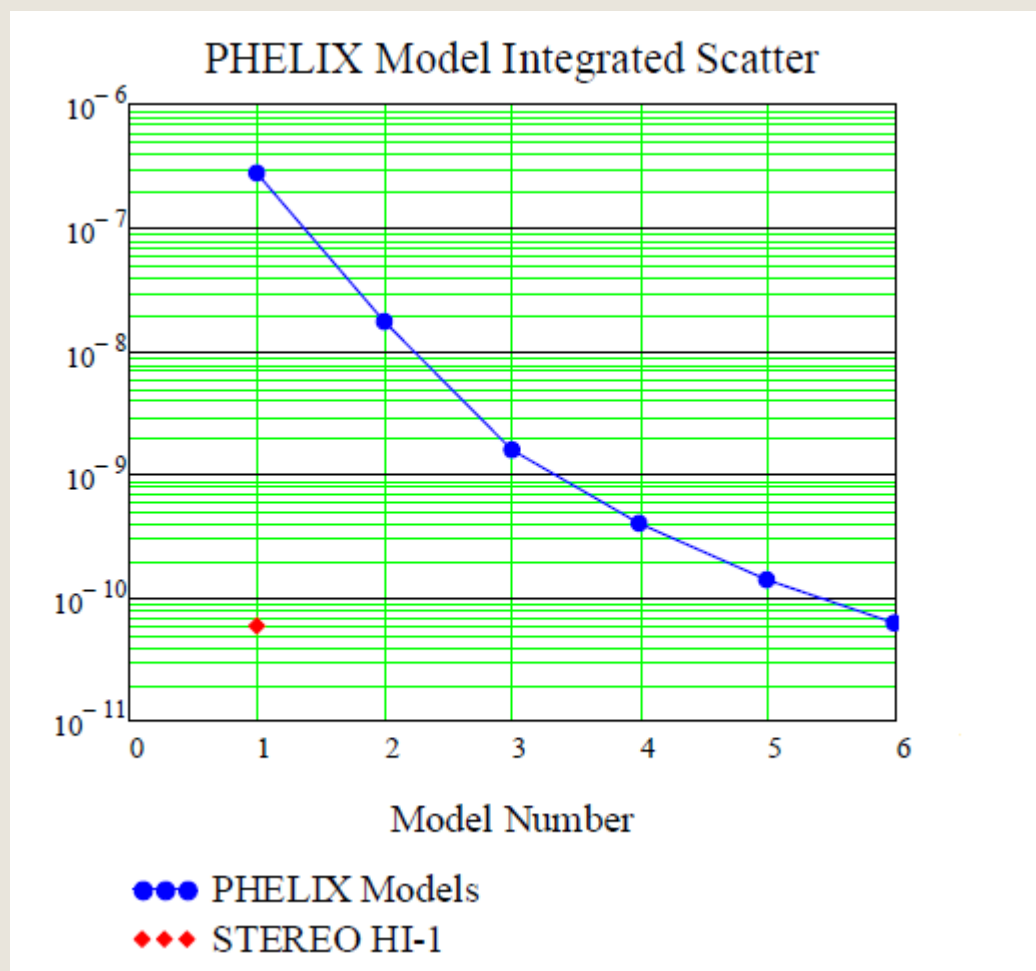
Instrument	FOV Diameter	FOV edge Closest to Sun Centre	Offset from Sun Centre
PHELIX	30 degrees	2.65	17.65 degrees
STEREO HI-1	20 Degrees	3.65	13.65 degrees

- Whilst retaining a 5 vane forward baffle, we studied how this could be achieved with original scattered light performance.

Model number	STEREO 1	PHELIX 1	PHELIX 2	PHELIX 3	PHELIX 4	PHELIX 5	PHELIX 6
Pupil Radius,mm	8	8	7	6	6	6	6
Length,mm	550	550	550	550	600	650	700
Diffraction Angle	1.322	0.363	0.615	0.867	1.022	1.149	1.254
Integrated Scatter	5.9e-11	2.8e-7	1.75e-8	1.58e-9	4e-10	1.4e-10	6.2e-11

- Based on the same general design, the STEREO/HI scattered light performance could only be achieved by reducing the size of the entrance aperture (reduces signal to noise ratio) AND increasing the instrument length by 150mm.

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Coronagraphic Imaging

In order to respond to emerging coronal imaging opportunities (e.g. ESA SSA), RAL Space (in collaboration with other institutes) are also base-lining a design for a compact space weather coronagraph.



Compliance with ESA's stated goals

Parameter	Requirement (with goal in brackets)	Proposed Baseline Design
Power	7 W (5 W)	11 W + heaters and mechanisms
Mass	12 kg (10 kg)	< 12 kg
Volume	0.015 m ³ (0.01 m ³)	0.04 m ³
Lifetime	10 years	TBC
Field of View	1.5 – 20 R (1.2 – 20 R)	3 – 30 R
CME Velocity Detection Range	400 – 3000 km/s (300 – 3500 km/s)	300 – 3500 km/s
Resolution	<10"	53"
SNR	>10 in corona at 20 R	>2 for at R ≤ 20 for 10 s exposure



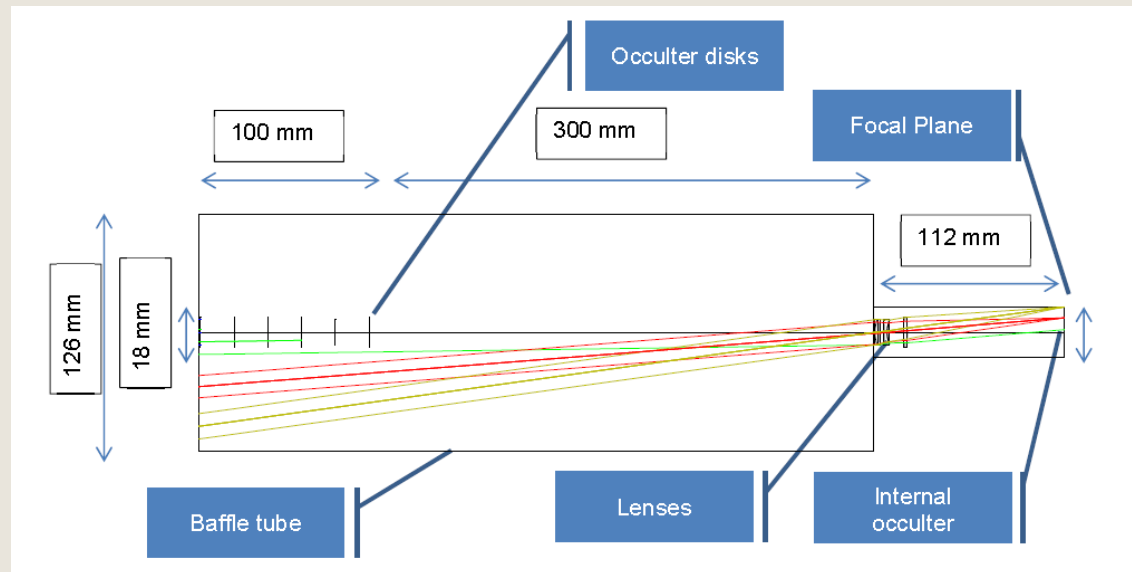


Design Trade-Offs

- **Field of view versus size and complexity**
 - Especially lower limit on FoV (influences complexity of baffle design)
- **Detector technology**
 - CCD vs CMOS
- **Aperture, waveband and exposure time**
 - Aim to maximise throughput without over-complicating optical design
 - Exposure time constrained by CME velocity and pointing stability
- **On-orbit versus on-ground processing**
 - Limited telemetry budget
 - Prefer to process on-ground where possible
- **Orbit**
 - Options are L1, L4/L5, GEO or LEO
 - L1 or L4/L5 are most credible
 - Different orbits place different constraints on instrument thermal design

Preliminary optical Design

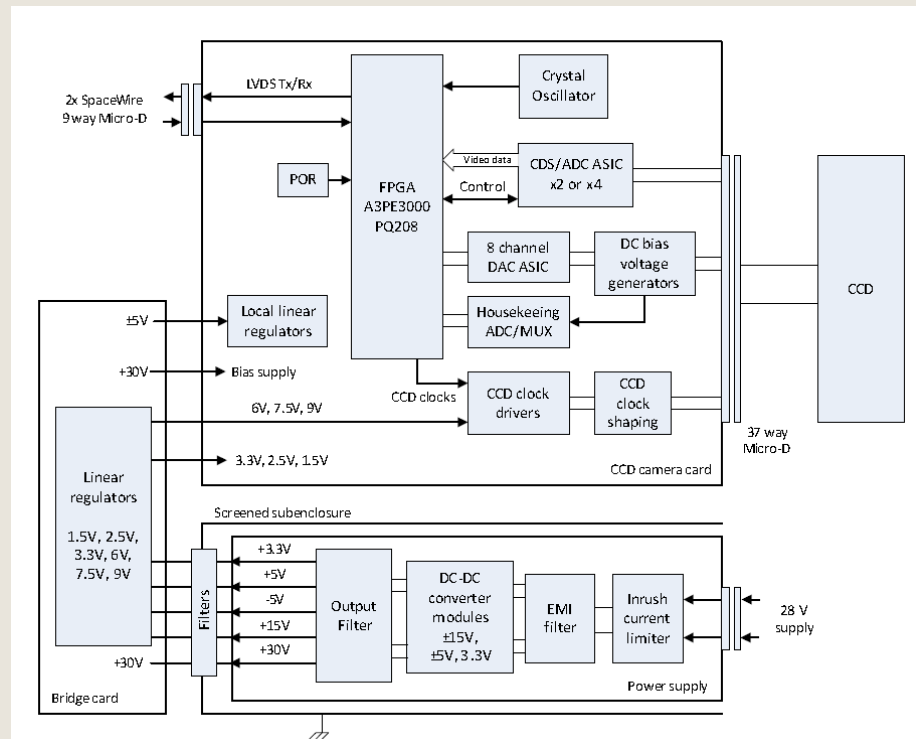
- Compact design with external occulter, objective lens and internal occulter in front of detector – no Lyot stop and relay lens
- Follows approach proposed by NRL¹
- Allows compact design without too much compromise to stray light rejection (TBC – see later)
- 1k x 1k detector – gives 53" / pixel at 30 R FoV



¹Theoretical study of the occulted solar coronagraph, Qian Gong et al, Proceedings of SPIE Vol. 5526, pp 208 – 219 (2004)

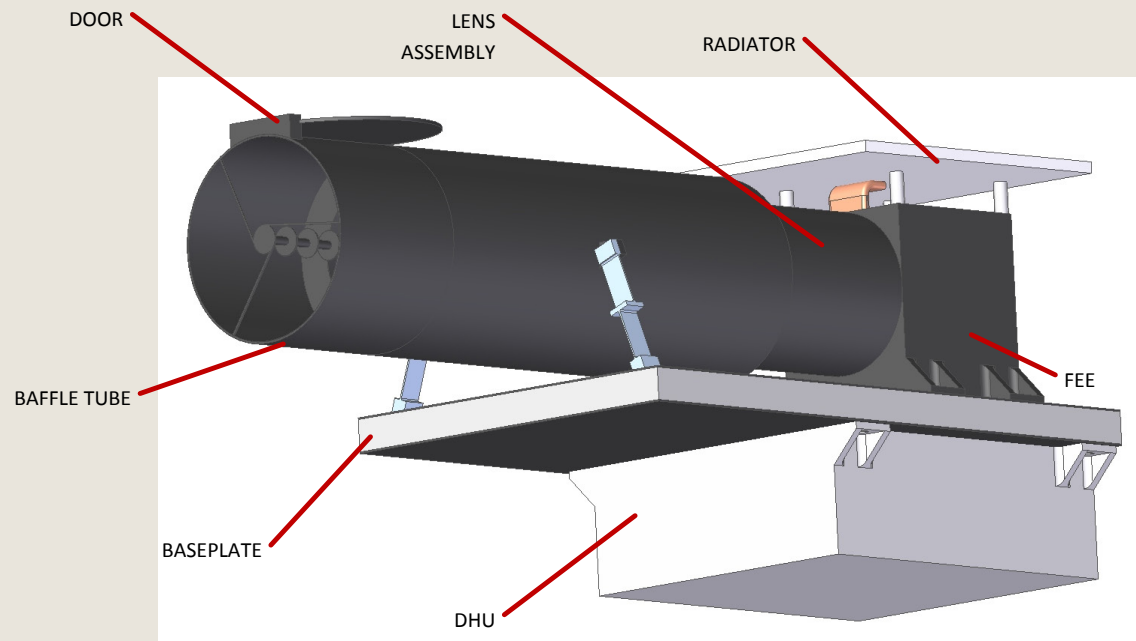
Detector & Front End Electronics

- ITAR-free version of the electronics developed by RAL Space for SDO and GOES
- e2v CCD-230
 - 2k x 2k 15 um pixel with on-chip binning to 1k x 1k
- CCD preferred to CMOS
 - On-chip binning; greater dynamic range; better linearity



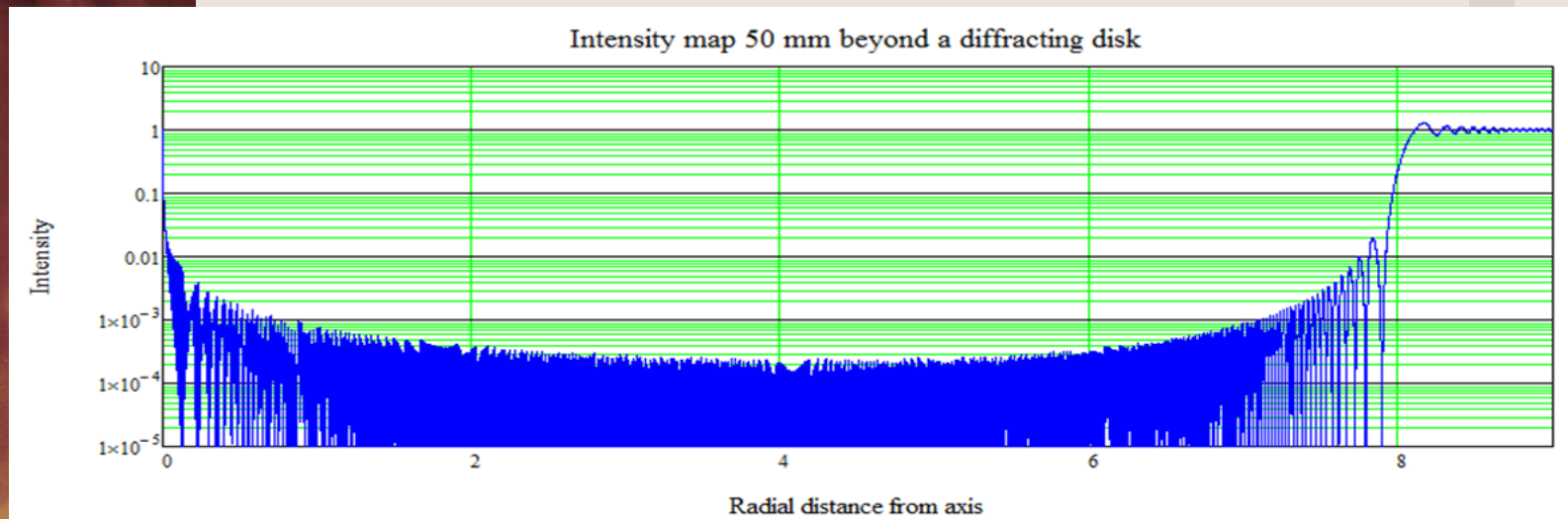
Baseline design

- 600 x 250 x 250 mm
- Basic CAD model worked up
- Includes data handling unit and thermal control
- Aim to minimise required spacecraft resources
- Re-use mechanical design heritage from similar sized RAL camera systems



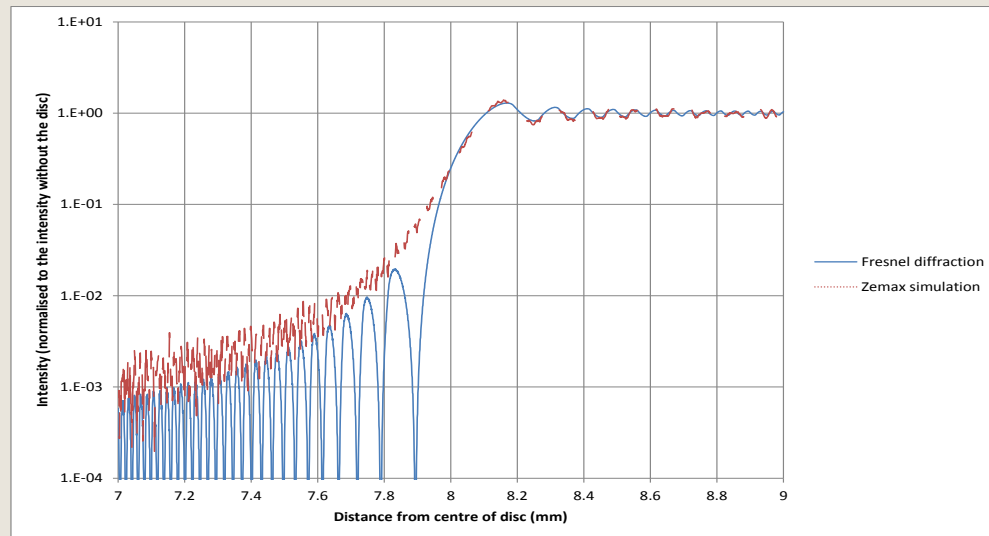
Occulter design

- Preliminary work started at RAL on occulter design
- Modelling of efficiency of multiple-disc external occulter
- Predict diffracted intensity in the shadow of the occulter from first principles (Fresnel diffraction) for simple geometry
- Code checked by calculating in Fortran and Mathcad with comparison of results – good agreement




Occulter design

- Build model in optical design code (e.g. Zemax, ASAP) and check against prediction from first principles for the simple case – good agreement
- Gives confidence that the model is correct
- Next steps:
 - Build optical model and explore optimisation of baffles
 - Compare efficiency of the proposed design against traditional 3 stage coronagraph



Summary

- RAL Space scientists  designing and building space instruments (and so do our engineers).
- We are seeing a resurgence in opportunities for doing so!
- Many are space weather related; scientists will do science with “space weather” instruments!

